



**BRUSHLESS** 

- MRV BRUSHLESS SERVO MOTORS
- AXIOM® DV SERVO DRIVE
- AXIOM® PV SERVO CONTROLLER/DRIVE
- SSC CONTROLLER
- JS JOYSTICK INTERFACE
- SIT HAND-HELD INTERFACE

## Axime Brushless Servo System

#### APPLICATION BENEFITS

- Extremely smooth and quiet operation
- Good for high torques [up to 45 in-lbs. (5.08 N-m) continuous, 140 in-lbs. (15.82 N-m) peak]
- Good for high speeds, up to 6,000 RPM
- High resolution, 4,000 counts per revolution
- Provide torque control
- Good for short, repetitive moves
- Maintenance free with no moving contacts

#### **MOTOR**



#### MRV - Brushless Servo Motors

- Rugged, with large shafts and bearings, IP65
- Convenient MS connectors
- Common flanges (NEMA 17, 23, 34 and 56)
- Integral temperature sensor and 1000 line encoder
- Gearhead reduction available in gear ratios of 5.5:1 and 10:1 when selected with Tol-O-Matic screw-drive actuators

#### **DRIVE**



**BRUSHLESS** 

**Overview** 

#### Axiom DV - Servo Drive

- Designed to drive MRV motors
- Peak current ratings of 10A, 20A and 30A
- State-of-the-art vector commutation and current control for efficient highbandwidth servo performance
- Simple Windows®-based software for set-up and installation

#### **DRIVE - CONTROLLER**



#### Axiom® PV Controller/Drive:

- Combines into one unit:
  - PLC: with real-time scan, 175 rung ladder logic
  - Motion Controller: with 1.5 axis, event triggering, motion pause and resume, point & click editor
  - Axiom drive: with all features listed above

 Includes Tol-O-Motion™ Axiom Motion Control Software and intuitive point and click sequential program and PLC ladder logic editors

#### **CONTROLLER**



#### SSC Controller:

- Performs any motion task including jogging, point-to-point positioning, linear and circular interpolation, electronic gearing, camming and contouring
- Multitasking feature permits simultaneous execution of four independent applications programs
- Tol-O-Motion SSC Motion Control Software allows setup & programming with easy-to-use Windows<sup>®</sup> interface
- Up to 4 axes per unit up to 4 units can be daisy-chained
- 4M non-volatile EEPROM memory for executing custom application programs - permits stand-alone operation
- Relative and absolute positioning with more than ± 2,000,000,000 counts per move
- Inputs: opto-isolated dedicated for home, abort, forward and reverse limits, 8 uncommitted; 7 analog inputs
- Outputs: 8 programmable

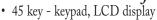
#### **INTERFACES**



#### **IS** - **Joystick**

• Use with SSC joystick teach mode

### SIT - Hand-held interface



• for use with SSC

Host compatible PC



## FEATURES AND SPECIFICATIONS



**COMPATIBILITY:** SYSTEM: BRUSHLESS MOTORS: MRV DRIVE: AXIOM DV **AXIOM PV** CONTROLLER: SSC

INTERFACE: JS

**AXIOM PV** 

### MRV Brushless Servo Motors

Tol-O-Matic's MRV series brushless servo motors provide a wide range of rated torques and speeds for applications requiring long life under continuous, difficult environment operation. These motors are designed for maximum power density. The MRV series motor come with an internally mounted 1000 line encoder.

#### FEATURES

- Rugged industrial enclosures
- Large shafts and bearings for longer life with high radial and axial loads
- · Dual convenient MS connectors to simplify motor termination and provide excellent noise immunity
- Common industrial mechanical flanges (NEMA 17, 23, 34, 56)
- Integral 1000 line TTL encoder with differential line driver outputs
- · Ideally suited for use with Axiom DV drives (motor parameters are stored with drive) - torque/speed curves shown on the following pages reflect MRV motors with Axiom drive performance.
- Internal thermal protection
- IP65\* rated (except MRV11)
- \*Totally protected against dust and low pressure jets of water.



#### **BRUSHLESS**

#### **MRV Motors**

- Features
- Specifications

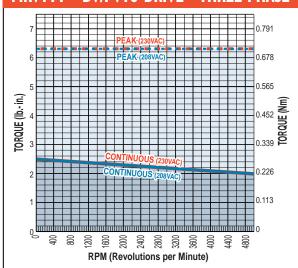
#### **SPECIFICATIONS**

Model	KE (1)	KT	(2) R	esistanc (3)	e Rotor	Inertia R	Therma esistan	al Cont. ice Torq		Peak Toro		Max. I Speed	nductance (4)	Wei	ight
	Volts/1000RPM	lb-in/amp	N-m/amp	Ohms	lb-in <sup>2</sup>	kg-m² x 10 <sup>6</sup>	°C/W	lb-in	N-m	lb-in	N-m	RPM	mΗ	lbs	kgs
MRV1	6.06	0.893	0.100	2.24	0.020	5.72	_	2.50	0.28	12.50	1.41	5,000	1.63	1.16	0.53
MRV2	<b>21</b> 8.80	1.290	0.144	2.22	0.053	15.58	1.80	3.75	0.42	11.31	1.28	6,000	1.81	2.20	1.00
MRV2	<b>22</b> 14.50	2.120	0.237	2.04	0.099	28.90	1.30	7.50	0.85	22.50	2.54	6,000	2.10	3.10	1.40
MRV2	<b>23</b> 21.80	3.190	0.357	2.73	0.143	41.70	1.23	11.25	1.27	33.81	3.82	6,000	2.95	4.00	1.80
MRV2	<b>24</b> 29.00	4.250	0.476	3.36	0.193	56.33	1.16	15.63	1.77	46.88	5.30	6,000	3.81	5.00	2.30
MRV3	<b>14</b> .80	2.170	0.243	1.10	0.386	112.85	0.72	17.00	1.92	85.00	9.60	6,000	2.60	8.00	3.60
MRV3	<b>32</b> 22.20	3.250	0.364	0.80	0.694	203.02	0.58	30.00	3.39	150.00	16.90	6,000	2.50	11.50	5.20
MRV3	<b>3</b> 25.90	3.790	0.424	0.60	1.006	294.47	0.56	44.00	4.97	220.00	24.90	6,000	2.10	14.00	6.35
MRV5	<b>1</b> 48.90	7.150	0.801	0.54	2.531	740.75	0.72	80.00	9.04	240.00	27.10	3,000	3.06	26.00	11.80

ALL RATINGS TYPICAL AND AT 77°F (25°C) UNLESS OTHERWISE NOTED. WINDING TEMPERATURE AT 257°F (125°C).

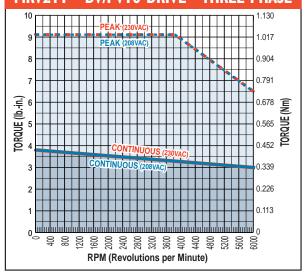
(1) L-L, RMS (±10%) (2) PER PHASE, RMS (±10%) (3) L-L DC RESISTANCE (±10%) (4) L-L (±15%)

## MRVIIY • DV/PVIO DRIVE • THREE-PHASE

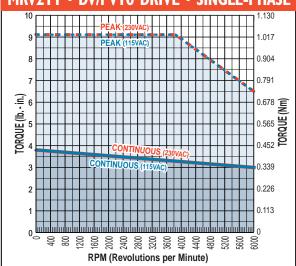


TORQUE (lb. - in.) 200 1600 2000 2400 2800 3200 3600 4000 **RPM (Revolutions per Minute)** 

#### MRV21Y • DV/PV10 DRIVE • THREE-PHASE



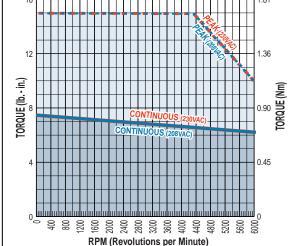
#### MRV2 I Y • DV/PV I O DRIVE • SINGLE-PHASE



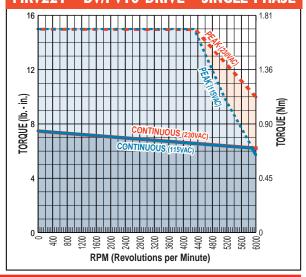
**BRUSHLESS** 

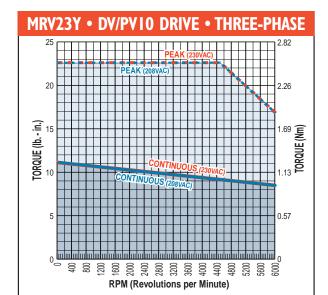
**MRV Motors** · Performance data

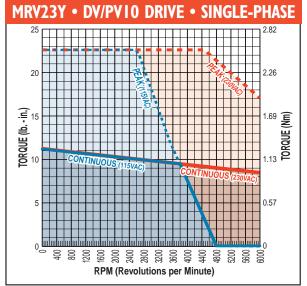


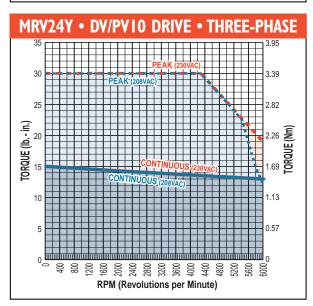


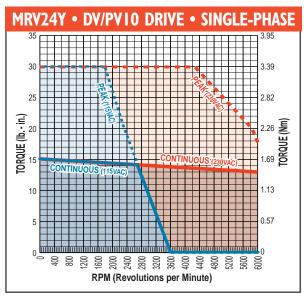
#### MRV22Y • DV/PV10 DRIVE • SINGLE-PHASE









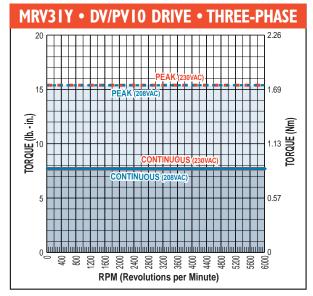


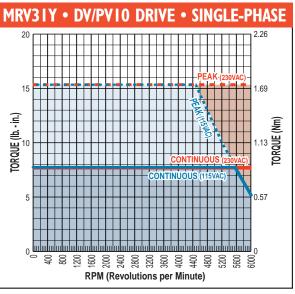


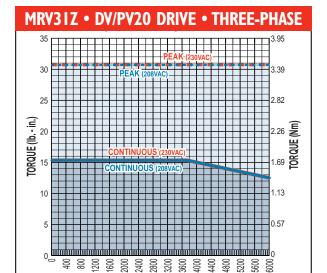
#### **BRUSHLESS**

#### **MRV Motors**

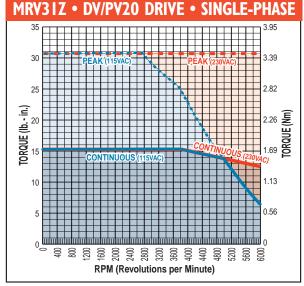
· Performance data







**RPM (Revolutions per Minute)** 

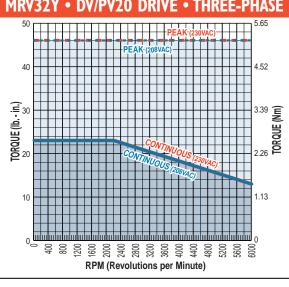


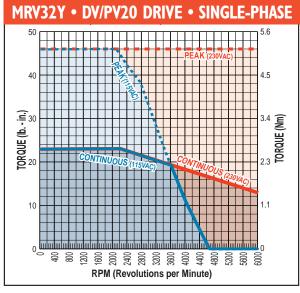


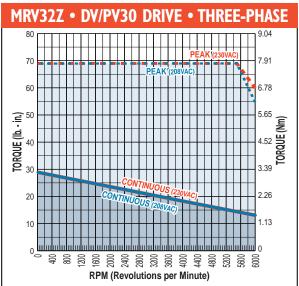
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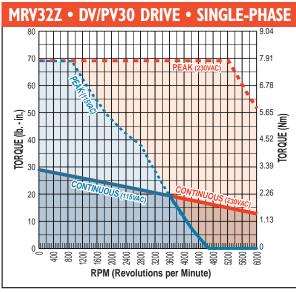
#### **MRV Motors**

· Performance data

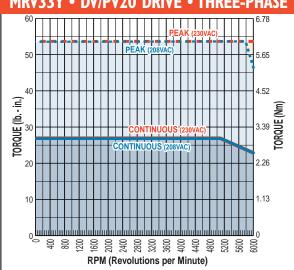




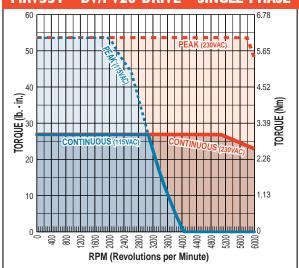




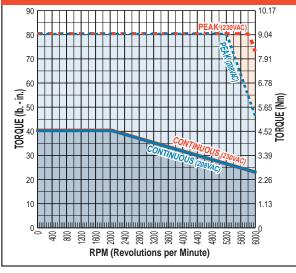




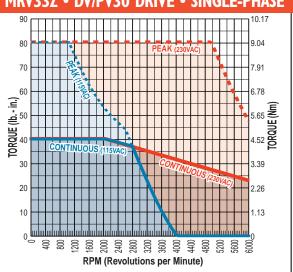




#### MRV33Z • DV/PV30 DRIVE • THREE-PHASE





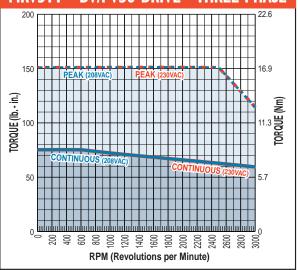


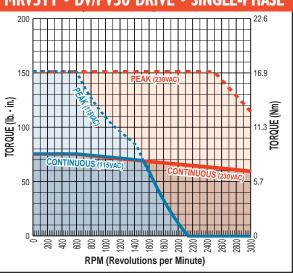


#### **BRUSHLESS**

#### **MRV Motors**

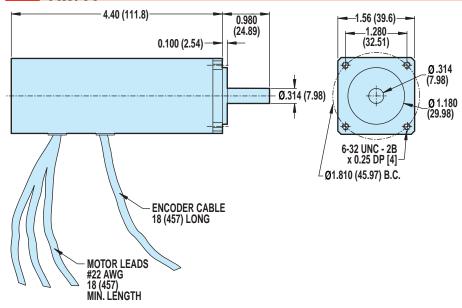
· Performance data





## MRV Brushless Servo Motors DIMENSIONS

#### **MRVII**



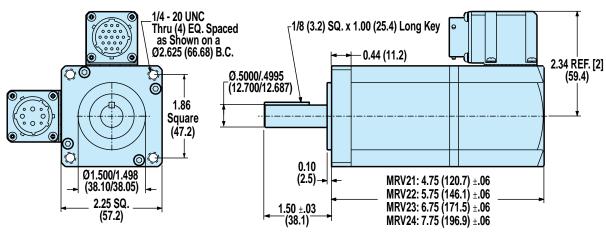
### MRV21, 22, 23, 24



#### **BRUSHLESS**

#### **MRV Motors**

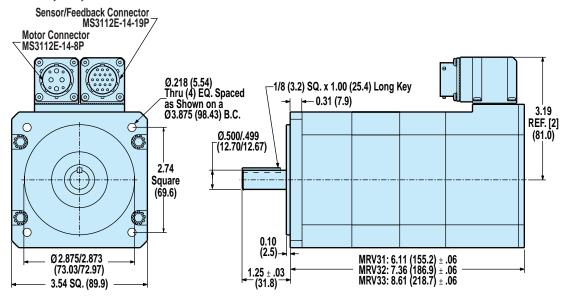
Dimensions



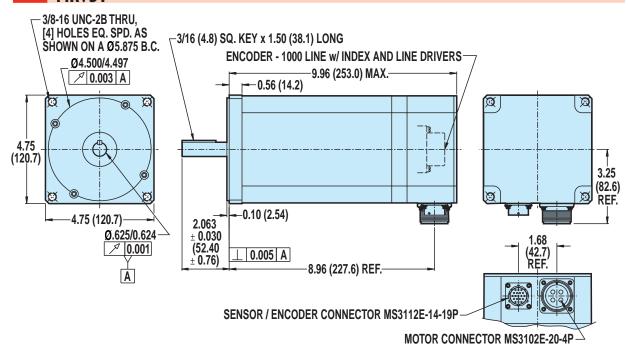


## MRV Brushless Servo Motors DIMENSIONS

### MRV31, 32, 33



#### MRV51





#### **BRUSHLESS**

#### **MRV Motors**

• Dimensions

## **4 Mine** Gearhead Reduction SPECIFICATIONS AND DIMENSIONS

#### **COMPATIBILITY:**

SYSTEM: BRUSHLESS MOTORS: MRV

**ACTUATORS: ALL** TOL-O-MATIC **SCREW DRIVES** 

#### **COMPATIBILITY:**

SYSTEM: STEPPER

MOTORS: MRS

**ACTUATORS: ALL** TOL-O-MATIC

**SCREW DRIVES** 

#### COMPATIBILITY:

SYSTEM: BRUSHED DC

MOTORS: MRB **ACTUATORS: ALL** 

TOL-O-MATIC **SCREW DRIVES** 



Reflected inertia is inertia at motor side of gearhead. § Only available on RSA64 LMI

For a complete part listing of screw-drive motor and gearhead mounting kits referencing actuator/motor/coupler compatibilities, refer to document 3600-4631 available on the Literature/Axidyne/Part Sheet section of

our web site at: www.tolomatic.com.

For those applications requiring reduction for inertia matching or higher torque at lower speeds, Tol-O-Matic offers high efficiency, single stage, true planetary gearheads. Gear ratios of 5.5:1 and 10:1 are available and are compatible with 23- and 34-frame MRV Brushless Servo, MRS Microstepping and Brushed DC motors.

#### **SPECIFICATIONS**

Efficiency:	85%
Backlash:	less than 10 arc minutes
Max. Input Speed:	5000 RPM

CONFIG		FRAME	GEAR		ECTED RTIA*	INPUT SHAFT	WEI	GHT
NO.	NO.	SIZE	RATIO	lb-in <sup>2</sup>	kg-m²	DIA. (in)	lbs	kgs
GHJ20	3600-6151	23	5.5 :1	0.0213	6.22	0.500	2.00	0.91
GHJ21	3600-6152	23	10:1	0.0181	5.30	0.500	1.98	0.90
GHJ30	3600-6154	34	5.5 : 1	0.1131	33.09	0.500	4.60	2.09
GHJ31	3600-6155	34	10:1	0.0888	25.96	0.500	4.78	2.17
GHJ32§	3600-6156	34	10:1	0.0888	25.96	0.500	4.81	2.18

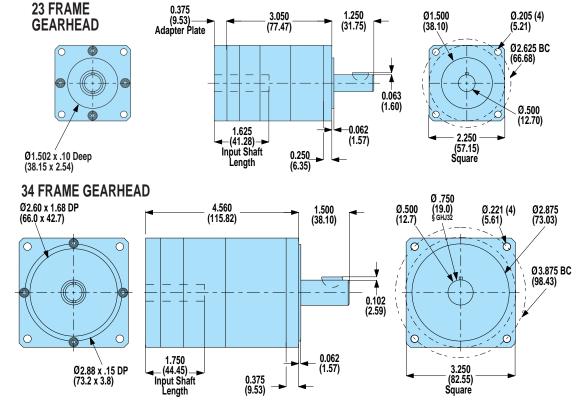


#### **BRUSHLESS**

#### **Gearhead Reduction**

- · Specifications
- Dimensions

### 23- AND 34-FRAME GEARHEADS



Unless otherwise noted, all dimensions shown are in inches (Dimensions in parenthesis are in millimeters)

## Axine AXIOM® DV Brushless Servo Drive

COMPATIBILITY:
SYSTEM: BRUSHLESS
MOTORS: MRV
DRIVE: AXIOM DV
CONTROLLER: SSC
INTERFACE: JS





 CONSIDER THE AXIOM PY FOR ALL OF THE FEATURES OF THE AXIOM DY, PLUS AN INTEGRAL CONTROLLER, & PLC ELIMINATING THE NEED FOR THE SSC CONTROLLER

The Axiom series of brushless and brushed servo drives combine high-speed accuracy with user friendly set-up and diagnostics. The Axiom DV series is a state-of-the-art DSP controlled digital vector commutated drive for a full range of brushless servo motors. DV series drives are available in 10, 20 and 30 Amp peak ratings (3 sec). All come with convenient pluggable screw terminal connectors and offer fast, easy set-up and installation for use in a wide variety of applications.

#### **AXIOM® DV DRIVE FEATURES**

- Space vector commutation provides better bus voltage utilization than traditional sine drives for improved speed/torque curves
- Flux vector current control provides more accurate high bandwidth control of torque producing current for better efficiency and more torque over the full speed range than with traditional sine drives
- Drives MRV series brushless servo motors
- Autophasing eliminates the need for Hall sensors in motors
- Pluggable screw terminal connectors eliminate the need for special connectors and secondary breakout terminal strips
- 115/208-230Vac input, single or 3-phase
- Short circuit, over current and over voltage protection prevents drive damage

- 25W or 50W internal regeneration
- External regeneration connections
- Analog torque and velocity command (±) 10V or step and direction (CW/CCW) position control
- Feedback from differential A+B and index channel optical encoder (5V)
- Maximum line count of 500,000/motor commutation cycle
- CW/CCW travel limit inputs
- Drive enable input
- Fault, enabled, and in-position outputs
- 3A brake relay
- 3 second peak ratings



#### BRUSHLESS

#### **Axiom DV Drive**

Features

### **AXIOM® DV SPECIFICATIONS**

SPECIFICATIONS	Axiom™	DV and DB Se	ries Drives	
Power	DVIO	DV20	DV30	
Continuous Current Rating:	5 Amps	10 Amps	15 Amps	
Peak Current Rating (3 sec):	10 Amps	20 Amps	30 Amps	
Max Input Current (single phase):	12.5 Amps	25 Amps	37.5 Amps	
Input Voltage (single/3-phase):	95Vac -130Vac (voltage range is			
Input Frequency:	47Hz - 63Hz			
<b>Command Sources</b>				
Analog Torque/Velocity Input:	± 10V, 16.4K ol	nm impedance		
Step and Direction or Step CW/Step CCW:	1 MHz maximur	n, 5V differentia	l or single ended dri	vers
<b>Serial Communication Port</b>				
Туре:	RS232			
Baud Rate:	19,200 baud			
Control Loops				
Туре:	All digital			
Loop Modes:	Torque, Velocity	and Position Co	ntrol	
Torque Update Rate:	10KHz			
Velocity Update Rate:	5Khz			
Position Update Rate:	2.5Khz			
Inputs and Outputs				
Dedicated Optically Isolated Inputs:	5Vdc - 25Vdc, 2 Can be configur		NABLE, CW LIMIT a sink current.	and CCW LIMIT.
Dedicated Optically Isolated Outputs:	3 optically isolat IN POSITION, EN Can be configur	IABLED and FAL	JLT.	
1 Dedicated Brake Relay Output:	N.O. contact, 24	Vdc, 115/230Va	ac, 3A max.	
Motor Feedback:	Incremental enc 4Mhz max., A/B 250 line min. wi 125 line min. wi	/I channels th a 4 pole moto	or	
Encoder Output:	Differential, 5Vd	c, A/B/I channels	3	
Connectors				
Serial:	9 pin D-Sub.			
Control and Feedback:	15 pin D-Sub.			
Power, Motor, Brake Relay, Regen:	Screw terminal I			
All Others:	Pluggable screw	terminal blocks	)	
Approvals	UL, CUL, CE			
Environmental				
Storage Temperature:	-40°C to 70°C			
Operating Temperature:	0°C to 50°C			
Humidity:	5% to 95%, nor			
Weight:	DV10	DV20	DV30	
	8 lbs	12 lbs	12 lbs	
	(3.7 Kg	(5.5 Kg)	(5.5 Kg)	



**BRUSHLESS** 

**Axiom DV Drive** 

Specifications

## Axiom® DV Brushless Servo Drive CONNECTORS

### **AXIOM® DV CONNECTORS**

#### TBI - BRAKE/REGEN

1 - Brake	4 - External Regen
2 - Brake	5 - Internal Regen
3 - Regen Common	

#### TB2 - MOTOR

1 - Motor R	3 - Motor T
2 - Motor S	4 - Motor Ground

#### TB3 - AC POWER

1 - L3	3 - L1
2 - L2	4 - Ground

#### J3 - OUTPUTS

1-	In Position +	4 - Enabled Out -
2 -	In Position -	5 - Fault Out +
3 -	Enabled Out +	6 - Fault Out -

#### J4 - INPUTS

1 - CW Limit	6 - Step/Step CW +
2 - CCW Limit	7 - Step/Step CW -
3 - Limit Common	8 - Direction/Step CCW +
4 - Enable +	9 - Direction/Step CCW -
5 - Enable -	

#### J6 - ANALOG INPUT COMMAND

1 - Analog Common	3 - Analog -
2 - Analog +	4 - Shield

#### **J7 - MOTOR ENCODER**

1 - Encoder +5V	6 - I+
2 - A+	7 -  -
3 - A-	8 - Common/Shield
4 - B+	9 - Motor Temp
5 - B-	

#### PI - BUFFERED ENCODER OUTPUT

1 - Reserved	8 - Common
2 - Reserved	9 - Encoder Out A+
3 - Reserved	10 - Encoder Out A-
4 - Reserved	11 - Encoder Out B+
5 - Reserved	12 - Encoder Out B-
6 - Reserved	13 - Encoder Out I+
7 - Reserved	14 - Encoder Out I-

#### P2 - COMMUNICATIONS

1 -	Reserved	6 - Reserved
2 -	RS-232 TX	7 - Reserved
3 -	RS-232 RX	8 - Reserved
4 -	Reserved	9 - +5Vdc (30ma MAX.)
5 -	Common	



#### **BRUSHLESS**

#### **Axiom DV Drive**

Connectors

## Axiom® DV Brushless Servo Drive SET-UP / CONFIGURATION

Axiom® Windows®-based PC setup software with a "control-panel" approach, makes it easy to get up and running fast. All set-up and configuration functions are performed using two main control-panel screens. Simple mouse-click commands automatically configure the control functions, eliminating layers of screens and menus. This approach also allows more relevant diagnostic information to be displayed simultaneously. All control screens include a command menu at the upper left to permit convenient selection of high-level functions and options.

A main menu is provided which allows selection of the main control panel functions, active comm port, etc. Tutorial selections are provided which emulate the main control-panel functions in an off-line manner and provide "help" text and function definitions/ descriptions so that users can actively familiarize themselves with the software without actually connecting a drive.

The software communicates with the drive using a standard RS-232 connection operating at 19,200 baud, using either comm port 1 or 2 of the PC. It can be installed and executed from any PC running Windows 95, 98, NT, 2000 or XP.

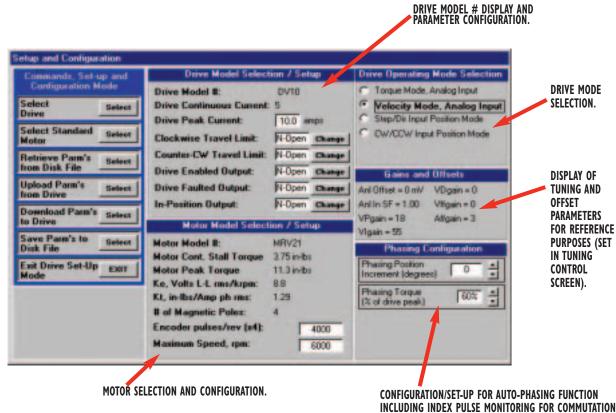
#### **SET-UP CONFIGURATION**

Drive operating mode and other options can all be selected/enabled from this screen. All set-up parameters can be uploaded and downloaded with a single click of the mouse. The parameter set can be saved to or retrieved from a disk file. Once downloaded to the drive, all parameters are stored in non-volatile EEPROM memory.



#### **BRUSHLESS**

Axiom DV Drive
• Set-up /
configuration



ACCURACY AND FASTER DETECTION OF FEEDBACK ERRORS.

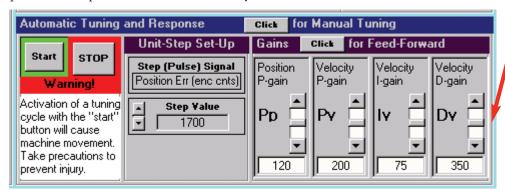
# A Mine Axiom® DV Brushless Servo Drive SET-UP / CONFIGURATION

#### TUNING AND DIAGNOSTICS

Use the 4-channel oscilloscope display for analysis of motion response when tuning and diagnosing. Scaling and format of the displayed traces can be easily modified. Values can be read directly off the traces at any point. Continuously updated bar graph displays allow important data to be viewed while motion is occurring. These displays are configured automatically based on drive operating mode they include peak detection functions and numeric displays. A status section of this control screen displays the current state of I/O and fault information.

Selecting "Drive-Tuning" from the command menu activates and displays the control functions for manual and automatic drive tuning. Use these controls to set-up and start actuation of an appropriate unit-step motion command and then enable automatic tuning parameter adjustment. Manual adjustments to tuning parameters can be easily accomplished.

The oscilloscope functions are used in conjunction with tuning, ensuring desired response goals are achieved. All tuning parameters are updated and activated immediately in the drive when modified (and also stored in EEPROM memory).



**TUNING CONTROLS ALLOW USER** CONFIGURABLE UNIT-STEP ACTUATION. AUTOMATIC AND MANUAL TUNING FUNCTIONS ARE PROVIDED. OPTIONAL VALUES FOR FEED FORWARD GAINS AND ANALOG OFFSETS CAN ALSO BE ENTERED.

4-CHANNEL OSCILLOSCOPE DISPLAY FOR SET-UP/TUNING AND SUBSEQUENT DIAGNOSIS. FLEXIBLE DISPLAY CONFIGURATION AND SLIDING VALUE INDICATOR, MAKE ANALYSIS QUICK AND EASY. INCLUDES USER CONTROLLED TRIGGER FUNCTIONS.

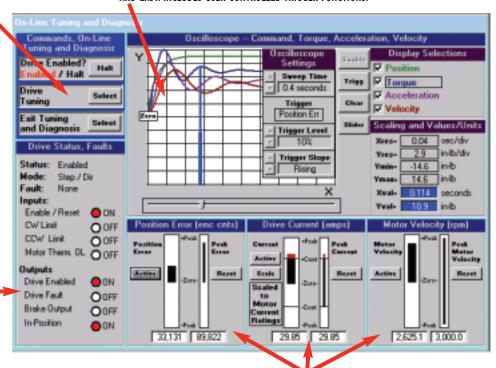
**ALL SOFTWARE SCREENS INCLUDE SEPARATE MENUS** OF HIGH-LEVEL **FUNCTIONS IN THE UPPER LEFT CORNER TO FACILITATE QUICK** TRANSITIONS BETWEEN SCREENS AND FUNCTIONS.

**CONTINUOUS DISPLAY OF** 

INFORMATION AS WELL AS

CRITICAL DRIVE STATUS

PHYSICAL STATE OF I/O.



DIAGNOSTIC BAR GRAPH DISPLAYS OF CRITICAL SYSTEM VALUES, UPDATED CONTINUOUSLY. INCLUDES PEAK DETECTION AND NUMERIC DISPLAY.

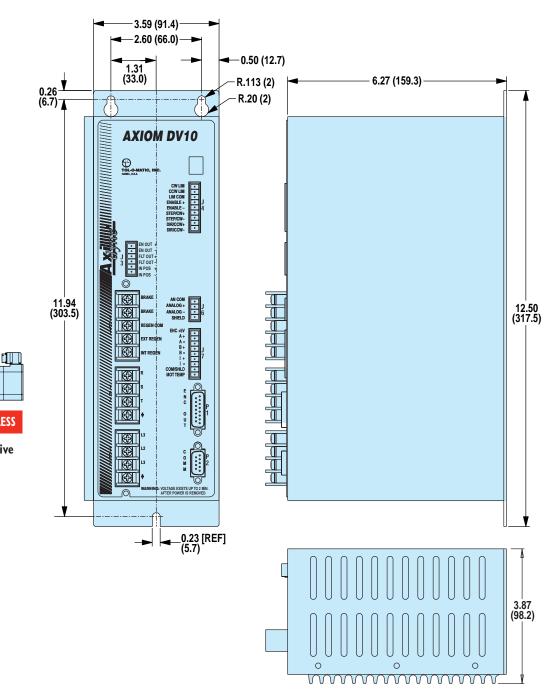
#### **BRUSHLESS**

#### **Axiom DV Drive**

Set-up / configuration

# Axiom® DV Brushless Servo Drive DIMENSIONS

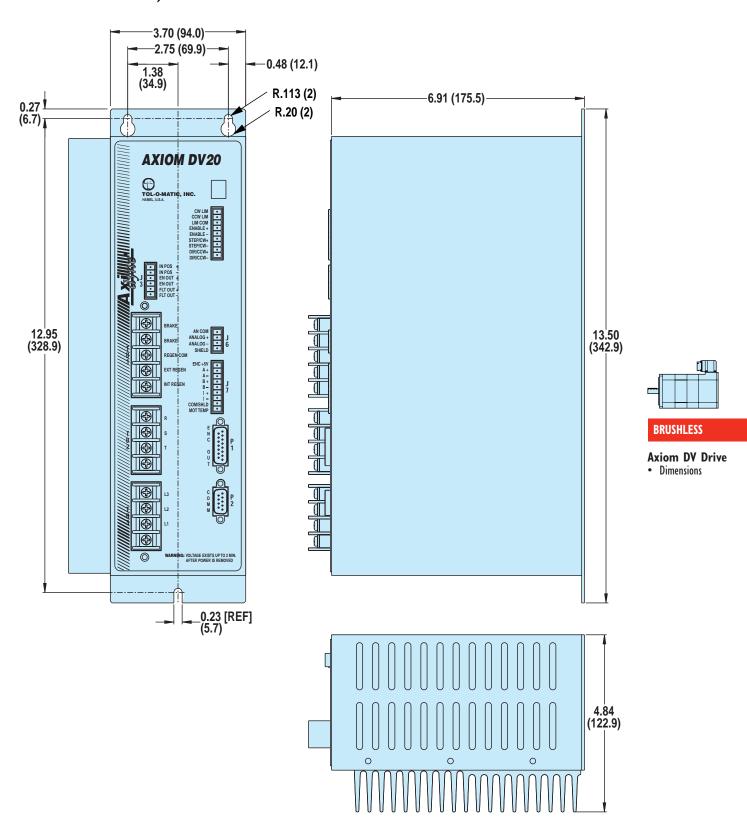
#### AXIOM DVIO





# Axiom® DV Brushless Servo Drive DIMENSIONS

### AXIOM DV20, DV30



## Axiom® PV Servo Drive/Controller



The Axiom PV sequential motion controller offers intuitive yet sophisticated functionality. The integrated PLC performs real-time scans on a separate thread and communicates through software rather than physical wiring. Windows®-based software utilizes a point and click sequential program and PLC ladder logic editor, allowing programming without learning code. The Axiom PV incorporates the same vector drive technology used in our Axiom DV drive. It is price competitive with integrated motion controllers/drives that do not offer PLC capability.

COMPATIBILITY:
SYSTEM: BRUSHLESS
MOTORS: MRY
DRIVE: AXIOM PY
CONTROLLER: AXIOM PY
INTERFACE: JS
SIT

#### **AXIOM® PV FEATURES**

#### PLC:

- Real-time scan supervisory function continuous from power-up
- Typical scan time of 2-4 milliseconds
- Ladder logic allows 175 rungs, 4 lines deep, 5 input operations, and an output coil
- Operations include: normally-open, normally-closed, logical invert, one-shot, output coil, latch, unlatch, timers and counters
- 64 character rung descriptor downloaded and uploaded with program
- Internal bit-flags for information transfer between controller and PLC

#### MOTION CONTROLLER:

- 1.5 axis (gearing to auxiliary axis)
- Commands include: absolute, incremental and velocity moves, branch to labels, subroutine calls, repeat loops, time delays, wait on conditions/inputs, output/flag control and parameter value changes including torque limit, following error, position band, follower gear ratio, and maximum velocity
- Event triggering based on intermediate positions
- Motion pause and resume
- Comment lines and labels down-loaded and uploaded with program

#### DRIVE:

- PV series drives use space vector commutation providing better bus voltage utilization than traditional sine drives for improved speed/torque curves
- Flux vector current control provides accurate high bandwidth control of torque producing current for better efficiency and more torque over the full speed range than with traditional sine drives
- Drives MRV series brushless servo motors or can be configured for customer specified linear or rotary 3-phase brushless servo motors
- Autophasing eliminates the need for Hall sensors in motors
- Drive enable input

#### **GENERAL:**

- · Modbus RTU and ASCII interface
- Pluggable screw terminal connectors eliminate the need for special connectors and secondary breakout terminal strips
- Short circuit, over current and over voltage protection prevents drive damage
- 25W or 50W internal regeneration
- External regeneration connections
- CW/CCW travel limit inputs
- Fault, enabled, and in-position outputs
- 3A brake relay
- 3 second peak ratings



BRUSHLESS

Axiom PV
Drive/Controller

Features

## Axiom® PV Servo Drive/Controller SPECIFICATIONS

### **AXIOM® PV SPECIFICATIONS**

SPECIFICATIONS	Axiom® P	V Series Drive	s	
Power	PV10	PV20	PV30	
Peak Output Current:	10 Amps	20 Amps	30 Amps	}
Continuous Output Current:	5 Amps	10 Amps	15 Amps	}
Continuous Output Power:	1.4 kW	2.8 kW	4.2 kW	
Input Voltage:	95 Vac -250 Va (voltage range is			
Input Frequency:	47Hz - 63Hz			
User Programming				
Language/Programming Environment:	Tol-O-Motion™ click sequential			
Firmware Field Upgradeable:	YES			
User Program Storage Capacity:	500 lines of gra and control instr			
PLC				
Connection/Capabilities:	Internal PLC with for programs of			4 msec, 10-12 msec s
Interface				
Interfaces supported:	Modbus RTU ASCII			
Inputs/Outputs				
General-Purpose Digital Inputs:	15 optically isola	ated 5-25 Vdc		
Inputs/Outputs:	Sinking/sourcing	y selectable		
General-Purpose Digital Outputs:	8 optically isolate	ed, 5-25 Vdc, 2	0 mA maximu	um
Communications:	Serial: RS-232,	19,200 baud ra	te	
Motor Feedback				
Input Modes:	Incremental with	ı index		
Maximum Input Frequency:	4 MHz (post-qua	adrature)		
Commutation Startup:	Auto-phase - no	Hall sensors re	quired	
Connectors				
Auxiliary Feedback, I/O, Analog I/O:	Wire trap screw	terminals		
Motor Feedback:	Wire trap screw	terminals		
Serial Port:	9-pin D-sub			
Main AC, Motor Power and DC Bus:	Screw terminal I	olock		
Approvals:	UL, CUL, CE			
Environmental				
Storage Temperature:	-40°C to 70°C (-	,		
Operating Temperature:	0°C to 50°C (32°	,		
Humidity:	5% to 95% non			
Weight	PV10		/20	PV30
	8.5 lbs (3.85 kg	) 12.5 lbs	(5.66 kg)	12.5 lbs (5.66 kg)



#### **BRUSHLESS**

### **Axiom PV Drive/Controller**

• Specifications

#### **AXIOM® PV CONNECTORS**

#### TBI - BRAKE/REGEN

1 - Brake	2 - Brake
3 - Regen Com	4 - External Regen
5 - Internal Regen	

#### TB2 - MOTOR

1 -	Motor R	2 -	Motor S
3 -	Motor T	4 -	Motor Ground

#### TB3 - AC POWER

1 -	L3	2 - L2
3 -	L1	4 - Ground

#### JI - Outputs

1 - Output 1 +	2 - Output 1 -
3 - Output 2 +	4 - Output 2 -
5 - Output 3 +	6 - Output 3 -

#### J2 - OUTPUTS

1 - +24Vdc	2 - 24Vdc Return
3 - Output 4 +	4 - Output 4 -
5 - Output 5 +	6 - Output 5 -

#### **J3 - OUTPUTS**

1 - Output 6 +	2 - Output 6 -
3 - Output 7 +	4 - Output 7 -
5 - Output 8 +	6 - Output 8 -

#### J4 - INPUTS

1 - +24Vdc	2 - 24Vdc Return
3 - Com 1 - 6	4 - Input 1
5 - Input 2	6 - Input 3
7 - Input 4	8 - Input 5
9 - Input 6	

#### J5 - INPUTS

1 - +24Vdc	2 - 24Vdc Return
3 - Com 7 - 12	4 - Input 7
5 - Input 8	6 - Input 9
7 - Input 10	8 - Input 11
9 - Input 12	

#### J6 - INPUTS

1 - Com 13 - 15	2 - Input 13	
3 - Input 14	4 - Input 15	

#### J7 - MOTOR ENCODER

1 - Encoder +5V	2 - A +
3 - A -	4 - B +
5 - B -	6-1+
7 -   -	8 - Com/Shld
9 - Motor Temp	

#### PI - Buffered encoder out/auxiliary encoder

1 - +5V Encoder	2 - Aux Encoder A +
3 - Aux Encoder A -	4 - Aux Encoder B +
5 - Aux Encoder B -	6 - Aux Encoder I +
7 - Aux Encoder I -	8 - Encoder Common
9 - Motor Encoder Out A	+
10- Motor Encoder Out A	4 -
11- Motor Encoder Out E	3+
12- Motor Encoder Out E	}-
13- Motor Encoder Out I	+
14- Motor Encoder Out I	-
15- Reserved	

#### P2 - COMMUNICATIONS

1 - Reserved	2 - RS-232 TX
3 - RS-232 RX	4 - Reserved
5 - Common	6 - Reserved
7 - Reserved	8 - Reserved
9 - +5Vdc (30mA Max.)	



**BRUSHLESS** 

# Axiom® PV Servo Drive/Controller PLC / Sequential program editors

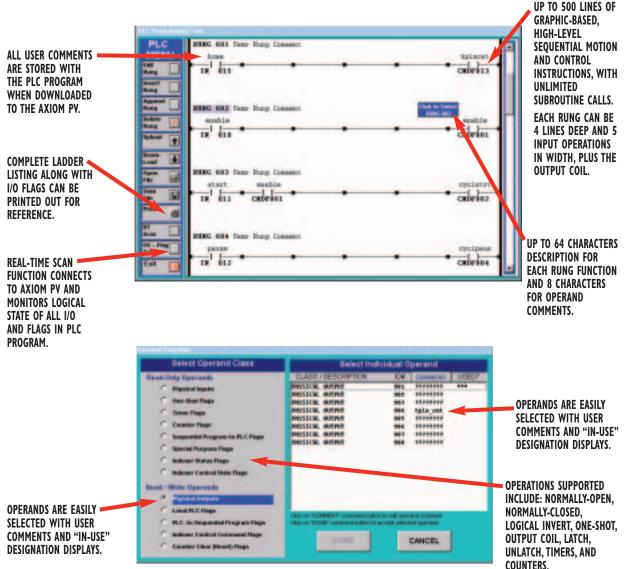
Axiom® PV set-up and configuration software has a similar look and feel to the Axiom DV software. A configuration option for motor selection and related parameters is included, along with a tuning and diagnostic mode. Help menus and control loop description information can be accessed from the main menu.

The Axiom PV also includes a point and click sequential program and PLC ladder logic editor. Instructions include incremental and absolute motion commands, branching (conditional and unconditional), subroutine calls, repeat loops, I/O control, time delays, etc. Use the PLC editor to enter and edit PLC programs, which run using an independent scan. The PLC program accesses all 15 inputs and 8 outputs of the Axiom PV, including general purpose and dedicated internal flags.

Both of these editors utilize easy icon/text driven selections, making the creation of motion profiles a snap (no code memorization required).

#### **AXIOM® PV PLC EDITOR**

The PLC Editor main menu allows user access to all editing functions along with a 175 rung ladder display. Rungs can be inserted at any point in the program and are easily edited by simply double-clicking with the mouse and selecting the desired functions from subsequent menus. The PLC program's real-time scan is continuous upon power-up and ranges from 2-4 milliseconds for a typical application, with 10-12 milliseconds for a maximum-length program.



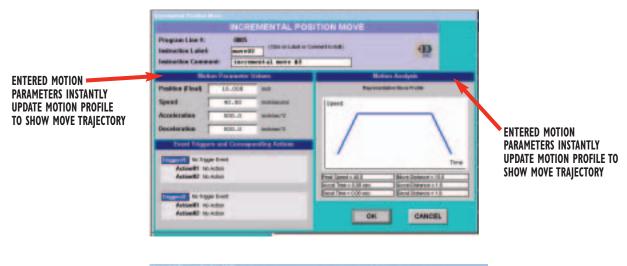
#### **BRUSHLESS**

#### Axiom PV **Drive/Controller**

 PLC / seguential program editors

### **AXIOM® PV SEQUENTIAL PROGRAM EDITOR**

The Sequential Editor main menu provides easy access to all essential program and display functions. Using a series of menus, the program guides the user through instruction selection. The Incremental Position Move window allows two separate trigger moves to be defined based on incremental position reached, physical input transition or flag from the PLC. Two actions can be commanded for each trigger event including torque limit or velocity change, output control or flag passing to PLC. This functionality allows an almost limitless combination of functions associated with a single move, while the PLC facilitates real-time control.





#### **BRUSHLESS**

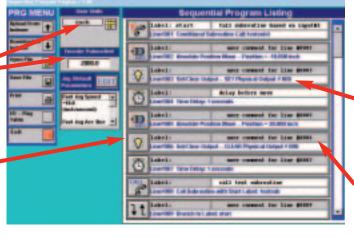
#### **Axiom PV Drive/Controller**

 PLC / sequential program editors

DECIMAL PRECISION **USER UNITS AND TWO JOG SPEEDS.** 

ALL USER COMMENTS AND LABELS ARE STORED WITH THE PROGRAM WHEN DOWNLOADED TO THE AXIOM PV.

SERIES OF INSTRUCTION **MENUS MAKE EASY SELECTION** OF PROGRAM CONTROL, MOTION COMMANDS, ETC.



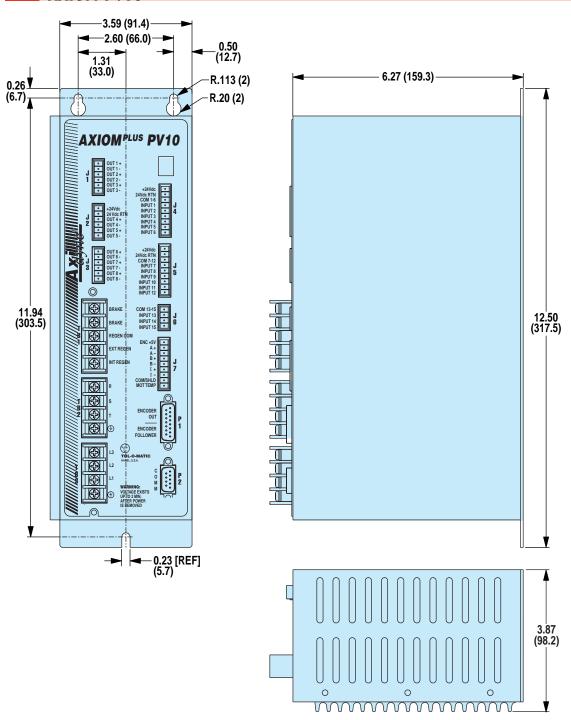
**CLICK DESIRED AREA** OF DISPLAY TO EDIT

**EACH INSTRUCTION INCLUDES AN 8 CHARACTER** LABEL USED FOR **BRANCHING, SUBROUTINE CALL DESTINATIONS AND A** 32 CHARACTER USER COMMENT.



# Axiom® PV Servo Drive/Controller DIMENSIONS

#### **AXIOM PVIO**





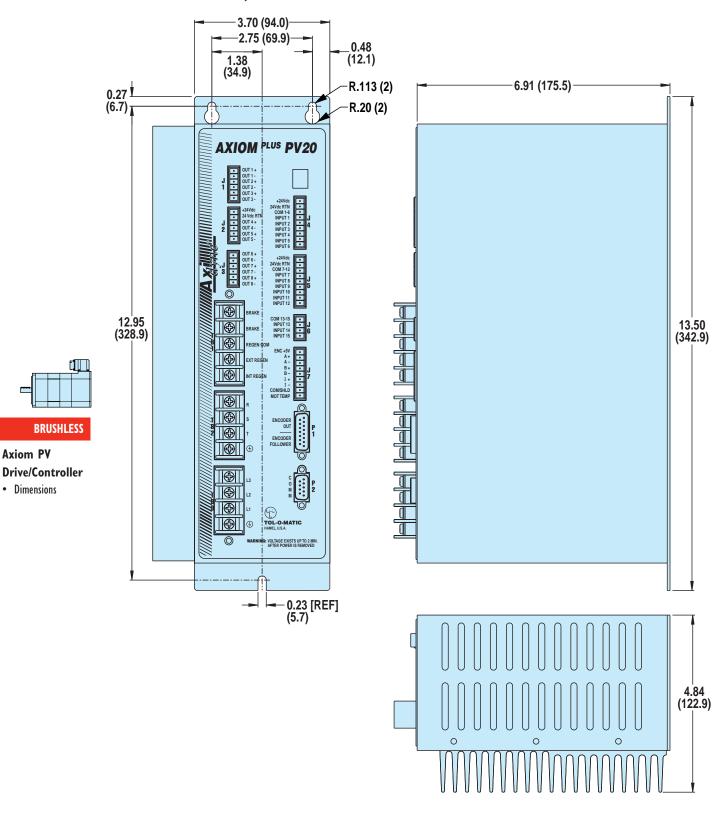
#### **BRUSHLESS**

## Axiom PV Drive/Controller

Dimensions

## Axime® Axiom® PV Servo Drive/Controller

### **AXIOM PV20, PV30**



## Axine SSC Multi-axis Servo/Stepper Controller

#### **COMPATIBILITY:**

SYSTEM: BRUSHLESS MOTORS: MRV

DRIVE: AXIOM DV

CONTROLLER: SSC

INTERFACE: JS SIT

#### **COMPATIBILITY:**

SYSTEM: STEPPER MOTORS: MRS

DRIVE: MSD

CONTROLLER: SSC

INTERFACE: JS

#### **COMPATIBILITY:**

SYSTEM: BRUSHED DC MOTORS: MRB

DRIVE: AXIOM DB

CONTROLLER: SSC INTERFACE: JS SIT



The SSC is a high-performance, state-of-the-art motion controller lesigned for stand-alone operation. This cost effective controller uses a 32-bit microprocessor, a sub-micron gate array, and Tol-O-Motion SSC software, to provide DSP performance without sacrificing ease of use.

Available with up to 4 axes per unit, purchase only the number of axes required. It can simultaneously control stepper and /or servo systems.

Designed to solve complex motion problems with superior precision, the SSC can be used for applications requiring jogging, vector positioning of multi-axis, 2-dimensional linear or circular interpolation, contouring and electronic gearing.

With the Tol-O-Motion SSC software there is no need to learn programming language. Complex motion control is made easy with an nterface that streamlines the entire programming process from setup to execution.

#### **SSC FEATURES**

- High performance motion control packaged in an industrial enclosure
- Uses a 32-bit specialized microcomputer and custom, submicron gate array for highest performance and speed
- Up to 4 axes per unit up to 8 units can be daisy-chained
- 125 µsec per axis servo update rate for high bandwidth
- Controls servo motors and/or step motors
- Sophisticated PID filter with velocity and acceleration feed forward for optimum precision
- 16 bit DAC for fine resolution control
- 256K RAM memory for holding and running active program up to 1000 lines x 80 characters
- 4M EEPROM memory for non volatile storage of custom application programs, parameters and arrays (8000 array elements x 30 arrays) — permits stand-alone operation
- Multitasking feature permits simultaneous execution of four independent applications programs
- Programmable acceleration and deceleration with profile smoothing to eliminate jerk
- Continuous vector feed of infinite number of linear and arc segments for smooth motion
- Selectable linear scale simplifies linear motion programming

- Contour mode for profiling along computer generated paths such as parabolic or spherical profiles
- Performs any motion task including jogging, point-to-point positioning, linear and circular interpolation, electronic gearing, cam and contouring
- Dedicated opto-isolated inputs for home, abort, forward and reverse limits noise immune
- Position feedback for each axis can be from analog signal or encoder
- Auxiliary encoder inputs and dual-loop damping ideal for backlash compensation
- Programmable event triggers for monitoring elapsed time, position, speed, and motion complete
- I/O functions, timers, and logic functions for executing PLC tasks
- 254 symbolic variables and 8000 element array space for data storage
- Internal, universal switching power supply for direct connection to AC outlet (115V or 230V)
- IDC connectors on front panel connect to DIN rail mounted screw terminal breakouts included
- Additional I/O available on request



#### BRUSHLESS

#### SSC Servo/Stepper Controller

Features

## SPECIFICATIONS SPECIFICATIONS

I/O Description (Inputs)

### SSC SPECIFICATIONS

SSC SPE	CIFICATIONS
Performance	
Servo Loop Cycle Time:	SSC 1: 250 µsec; SSC 2: 375 µsec SSC 3: 500 µsec; SSC 4: 500 µsec
Block Execution Time:	In contour mode, up to 1000 blocks (moves)/sec with full trajectory calculation
Position Accuracy:	· · · · · · · · · · · · · · · · · · ·
Velocity Accuracy:	Long-term: phase-locked, better than 0.003% Short-term: system dependent
Synchronization:	All axes in the same unit are perfectly synchronized and share the same servo cycle.
Position Capture Accuracy:	25 μsec with opto-isolation; 1 μsec if by-pass opto-isolation.
Parameter Ranges	
Position Range:	±2,147,483,647 counts/move; automatic rollover; no limit in jog or vector modes.
Velocity Range:	Up to 8,000,000 counts/sec
Acceleration/deceleration:	1,024 to 67,107,840 c/sec2
Error Limit:	±32,767 counts
Gear Ratio:	±127.9999
Filter Constants:	Kp: 0 to 1023.875 Kd: 0 to 4095.875 Ki: 0 to 2047.875
Motor Command Resolution:	16-bits or .0003 V
Step Motor Control Mode:	Full, half or microstep
Step Pulse Frequency:	2,000,000 pulse/sec
Number of Variables:	254
Array Memory Size:	8000 elements in up to 30 arrays
Program Memory Size:	1000 lines x 80 characters
Mechanical	1011 binb 0 Fll wide C Cll deep
Dimensions:	13" high x 2.5" wide x 6.6" deep
Weight: Inputs/Outputs	6 lbs.
Feedback:	Two channels of A/B quadrature per axis with third channel for index. In servo mode, includes auxiliary encoder inputs for each axis. Single ended or differential. Can be configured for quadrature, pulse and direction, or from analog inputs.
General Purpose Inputs:	8 opto-isolated inputs
General Purpose Outputs:	8 TTL outputs
General Purpose Analog Inputs:	7, ±10 V; 12-bit resolution (16-bit optional)
Dedicated Inputs per Axis:	
Dedicated Outputs per Axis:	amplifier enable
Available Power to Dr	
	1.5 Amp +12 V 750 mA -12 V 200 mA
Environment	32° to 158° F (0° to 70° C)
	37 IO 1981 FIUTIO /U* U.

Selectable Baud Rate: 300, 1200, 4800, 9600, 19200, 38400. Handshake mode available.

, ,	two channels in quadrature. The encoder can be $(\pm 12V)$ or TTL. Note: Encoders that produce output in a pulse and direction format can also be used.
Encoder Index I+:	Once-per-revolution encoder pulse; used in Homing sequence or Find Index command. Minimum index pulse width is 120 nsec.
Encoder, A-, B-, I-:	Optional differential inputs from encoder; used for enhanced noise immunity.
Auxiliary Encoder:	Inputs for additional encoder; used when encoders on both the motor and the load are required.
Abort #:	Stops commanded motion instantly and also aborts application program.
Reset #:	System reset.
Forward and Reverse Limit Switch #:	When active, inhibits motion in forward or reverse direction and also causes the limit switch subroutine #LIMSWI to execute.
Home Switch #:	Input for Homing (HM) and Find Edge (FE) instructions.
Input 1 - Input 8#:	Uncommitted inputs; can be defined by the user to trigger events or interrupt program.
Latch#:	High-speed position latch to capture axis position within 25 µsec (bypass opto-isolation for .1 µsec capture). AL command arms latch. Input 1, 2, 3, 4 latches X, Y, Z, W respectively.
Analog 1 - Analog 7:	Analog inputs that can be connected to external analog signals such as force or pressure transducers. Can also be used for position feedback. 12-bit resolution ADC for $\pm 10$ V input.
I/O Description (Outpo	uts)
Analog Motor Command:	$\pm 10\ V$ range signal for driving servo amplifiers; 16-bit resolution or .0003 V, 3 mA.
Amp enable:	Signal to disable and enable an amplifier. Amp enable goes low when a motor-off condition occurs. For step motors, this pin provides for reduced current when low.
Step Out:	pulses can be either active low or high. Upon Reset, the output will be low if the SM jumper is on, Tristate if off. The STEP OUT pin also provides the PWM signal for servo motors.
Direction:	Used with the STEP OUT signal to give direction to step motors or servo motors in the sign magnitude mode.
Error:	The signal goes low when the position error on any axis exceeds the limit specified by the error command, ER.
Output 1 - Output 8:	These 8 TTL outputs are uncommitted and can be designated by the user to toggle relays and trigger external events. The output lines are toggled by Set Bit (SB), Clear Bit (CB), Define Bit (OB), and OP instructions. Upon reset these signals will be low.

Encoder, A+, B+: Position feedback from incremental encoder with



### BRUSHLESS

#### SSC Servo/Stepper Controller

• Specifications

# SSC Multi-axis Servo/Stepper Controller CONNECTORS

### SSC CONNECTORS

SSC J2 Main; 60-Pin IDC	<u>;</u>			SSC	J3 Auxiliary Encode	er; 2	0-Pin IDC;
1 Ground	2	5 V		1	Sample Clock	2	Reserved
3 Error	4	Reset		3	B- Aux W	4	B+ Aux W
5 Switch Common	6	Forward	Limit - X	5	A- Aux W	6	A+ Aux W
7 Reverse Limit - X	8	Home -	Χ	7	B- Aux Z	8	B+ Aux Z
9 Forward Limit - Y	10	Reverse	Limit - Y	9	A- Aux Z	10	A+ Aux Z
11 Home - Y	12	Forward	Limit - Z	11	B- Aux Y	12	B+ Aux Y
13 Reverse Limit - Z	14	Home -	Z	13	A- Aux Y	14	A+ Aux Y
15 Forward Limit - W	16	Reverse	Limit - W	15	B- Aux X	16	B+ Aux X
17 Home - W	18	Output 1		17	A- Aux X	18	A+ Aux X
19 Input Common	20	Latch X	or Input 1	19	5 V	20	Ground
21 Latch Y or Input 2	22	Latch Z	or Input 3				
23 Latch W or Input 4	24	Abort Inp	out	SSC	J4 Driver; 20-Pin II	DC;	
25 Motor Command X	26	Amp Ena	able X	1	Motor Command X	2	Amp Enable
27 Motor Command Y	28	Amp Ena	able Y	3	PWM X/Step X	4	Sign X/Dir X
29 Motor Command Z	30	Amp Ena	able Z	5		6	Motor Com
31 Motor Command W	32	Amp Ena	able W	7	Amp Enable Y	8	PWM Y/Ste
33 A+ X 34 A- X	35	B+ X	36 B-X	9	Sign Y/Dir Y	10	
37 l+ X 38 l- X	39	A+ Y	40 A-Y	11	Motor Command Z	12	Amp Enable
41 B+Y 42 B-Y	43	l+Y	44 I-Y	13	PWM Z/Step Z	14	Sign Z/Dir Z
45 A+ Z 46 A- Z	47	B+ Z	48 B-Z	15	5 V	16	Motor Com
49 l+ Z 50 l- Z	51	A+W	52 A-W	17	Amp Enable W	18	PWM W/St
		l+ W	56 I-W	10	Cian M/Dir/M	20	Cround
53 B+W 54 B-W	55	I+ VV	30 I- W	19	Sign W/Dir W	20	Ground

	<b>33C</b>	JO AUXIIIATY ETICOU	er; z	U-FIII IDC;
	1	Sample Clock	2	Reserved
	3	B- Aux W	4	B+ Aux W
	5	A- Aux W	6	A+ Aux W
	7	B- Aux Z	8	B+ Aux Z
	9	A- Aux Z	10	A+ Aux Z
	11	B- Aux Y	12	B+ Aux Y
	13	A- Aux Y	14	A+ Aux Y
	15	B- Aux X	16	B+ Aux X
	17	A- Aux X	18	A+ Aux X
	19	5 V	20	Ground
	SSC	J4 Driver; 20-Pin II	DC;	
	1	Motor Command X	2	Amp Enable X
	3	PWM X/Step X	4	Sign X/Dir X
	5		6	Motor Command Y
	7	Amp Enable Y	8	PWM Y/Step Y
(	9	Sign Y/Dir Y	10	
_	11	Motor Command Z	12	Amp Enable Z
	13	PWM Z/Step Z	14	Sign Z/Dir Z
	15	5 V	16	Motor Command W
V	17	Amp Enable W	18	PWM W/Step W

### **BRUSHLESS**

Servo/Stepper Controller

Connectors

#### SSC 15 General I/O: 26-Pin IDC:

330	J3 General 1/0, 20-	1 1111 112	, , , , , , , , , , , , , , , , , , ,
1	Analog 1	2	Analog 2
3	Analog 3	4	Analog 4
5	Analog 5	6	Analog 6
7	Analog 7	8	Ground
9	5 V	10	Output 1
11	Output 2	12	Output 3
13	Output 4	14	Output 5
15	Output 6	16	Output 7
17	Output 8	18	Input 8
19	Input 7	20	Input 6
21	Input 5	22	Input 4 (Latch W)
23	Input 3 (Latch W)	24	Input 2 (Latch W)
25	Input 1 (Latch W)	26	Input Common (Isolated 5 V)

#### AC Power INputs; 4-PIN Detachable Screw Type:

Hot Conn	ects to 110 or 220 AC	
NC	No Connect	
Neutral	Return for AC	
Earth	Chassis input	

#### RS232 - Main Port; 9-PIN:

1 CTS - output	2 Transmit data
3 Receive data	4 RTS - input
5 Ground	6 CTS - output
7 RTS - input	8 CTS - output
9 5 V	

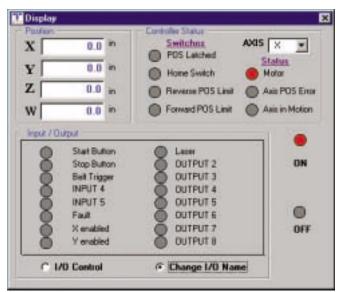
#### RS232 - Auxiliary Port; 9-PIN:

3 Transmit data 4 RTS - output 5 Ground 6 CTS - input	1 CTS	- input 2	2	Receive data -
5 Ground 6 CTS - input	3 Trans	smit data 4	4	RTS - output
	5 Grou	nd 6	3	CTS - input
7 RTS - output 8 CTS - input	7 RTS	- output 8	3	CTS - input
9 5 V	9 5 V			

## SSC Multi-axis Servo/Stepper Controller PROGRAMMING SOFTWARE

#### SSC PROGRAMMING SOFTWARE

Programming is accomplished through RS232 connection to a PC running Windows 95, 98, NT, 2000 or XP. Visual Basic panels guide the user through the complete setup process including communications and axis configuration. The user can then use other program options including Display, Jog, Teach, Programmer, Tune and Data Acquisition.





Jog

The Jog panels allow the user to easily setup independent motion or coordinated motion.



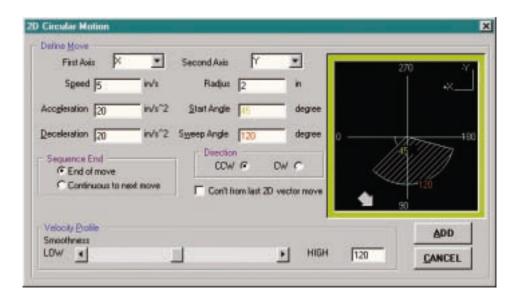
**BRUSHLESS** 

#### SSC Servo/Stepper Controller

Programming

## Display

The Display panel (shown above) allows the user to identify axis locations and status faults, limits, and I/O.

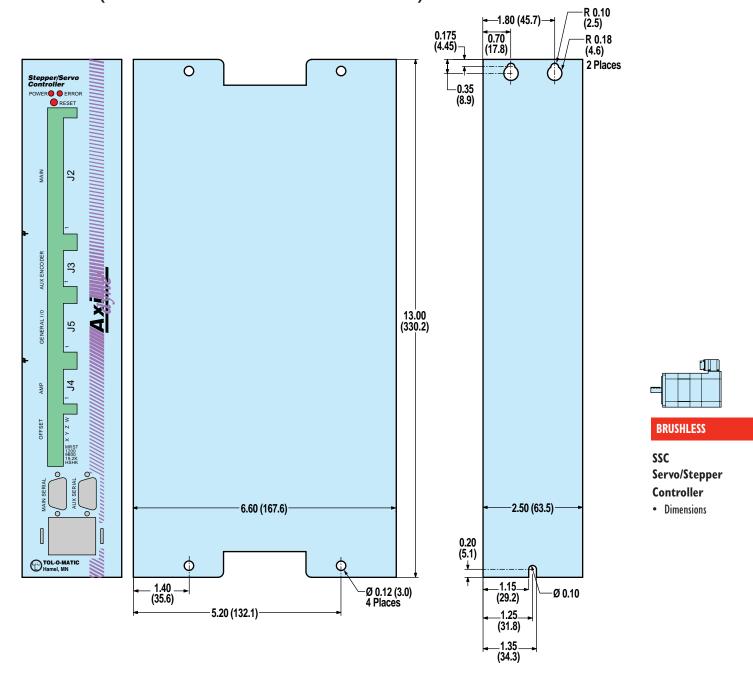


### **CIRCULAR MOTION**

The added feature of 2-dimensional circular programming, assists you in selecting start and sweep angles.

## Axine SSC Multi-axis Servo/Stepper Controller

### SSC (MULTI-AXIS SERVO/STEPPER CONTROLLER)



#### Products discontinued August 01, 2006: SSC Multi-Axis Controller, [ Stepper Motors & Control Products, I **Contact Tol-O-Matic for repair parts**

## SPECIFICATIONS AND DIMENSIONS

### **COMPATIBILITY:** SYSTEM: BRUSHLESS MOTORS: MRV

DRIVE: AXIOM DV

CONTROLLER: SSC INTERFACE: JS SIT

#### **COMPATIBILITY:**

SYSTEM: STEPPER

MOTORS: MRS

DRIVE: MSD

CONTROLLER: SSC

INTERFACE: JS

#### **COMPATIBILITY:**

SYSTEM: BRUSHED DC MOTORS: MRB

DRIVE: AXIOM DB

CONTROLLER: SSC

INTERFACE: JS



For simple setup of the SSC controller the JS joystick provides 2-axis manipulation. Used with the Joystick Teach mode of the Tol-O-Motion SSC software, moves can be made with velocity control, and then stored using a separate button integrated into the joystick housing.

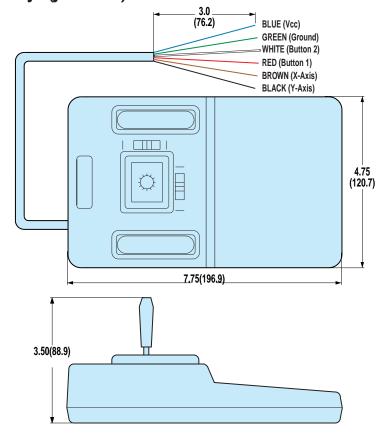
SPECIFICATIONS	JS Joystick
Joystick Travel	27° from design center in all directions
Mechanical Life Cycle	5 million (minimum)
Trim Movement (Optional)	±7° (total trim 14°) for each axis
Main Ball Pivot	Precision ground stainless steel
Stick Shaft	3/16" brass plated
Potentiometers	Set at center of resistance
Potentiometer Calibration	Thumb tab provides up to 114° of potentiometer calibration
Return to Center Repeatability	±1%
Deflection Force	0.14 lbs. at 27° at 2-7/8" from pivot point
Switches	2 elongated push-button switches
Cable	Integrated 7' (2.1m) cable with strain relief

#### **BRUSHLESS**

#### **JS** Joystic **User Interface**

- Specifications
- Dimensions

### JS (JOYSTICK) DIMENSIONS



Unless otherwise noted, all dimensions shown are in inches (Dimensions in parenthesis are in millimeters)

## **A** SIT – Hand-held, user interface

### **FEATURES AND DIMENSIONS**

#### **COMPATIBILITY:**

SYSTEM: BRUSHLESS MOTORS: MRV

DRIVE: AXIOM DV

CONTROLLER: SSC

INTERFACE: JS SIT

#### **COMPATIBILITY:**

SYSTEM: STEPPER MOTORS: MRS

DRIVE: AXIOM DB

CONTROLLER: SSC INTERFACE: JS

DRIVE: MSD CONTROLLER: SSC INTERFACE: JS **COMPATIBILITY:** SYSTEM: BRUSHED DC MOTORS: MRB

For user interaction with the SSC 1-4 axis multi-function controllers the SIT hand held user interface provides flexibility and setup simplicity. The Tol-O-Motion SS software (included with the SSC 1-4 controllers) has a setup page for use with the SIT to allow the controller to status the user, or to prompt the user for information, eliminating the need for a PC following setup.

#### **FEATURES:**

- 45 key, alpha-numeric tactile keypad
- 4 row by 20 character LCD display
- · Rugged, high impact ABS housing
- 7 foot (2.1m) RS232 cable with 9-pin "D" connector for connection to the SSC 1-4
- 5 Vdc power supplied from SSC 1-4 controller over RS232

SPECIFICATIONS	JS Joystick
Weight	8.0 oz. (.23 Kg.)
Character Set	ASCII with upper case transmit, upper and lower case receive
Case	Molded, high impact ABS with retractable hanger
Keypad	15 user-programmable function keys
Display	Transreflective LCD with 5 by 7 character font
Power Requirements	30 mA maximum, regulated, 5 Vdc ±5% (Received through RS 232 cable)
Speaker	Audible key click, bell and alert
Storage Temperature	-4° F (-20° C) to 158° F (+70° C)
Operating Temperature	32°F (0° C) to 122° F (+50° C)
Relative Humidity	10% to 90% non-condensing

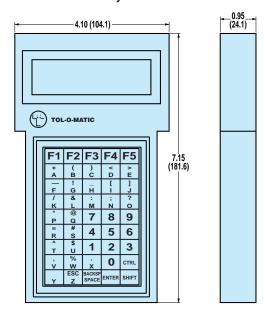


#### **BRUSHLESS**

#### SIT Hand-held **User Interface**

- Features
- Specifications
- Dimensions

### **SIT (HAND-HELD INTERFACE)**



### MRV MOTORS TO AXIOM DV DRIVE & AXIOM PV DRIVE/CONTROLLER

MRVII			•	TO: AXIOM DVIO, AXIOM PVIO					
Config Code	Replacement Part Number	Included with Drive	Туре	Description	Cable Length	Motor Size	CONNE Motor	CTORS AT Axiom DV/PV 10	Axiom DV/PV Size
_	_	YES	Power		18 in	All	Flying leads	Screw terminal	10
_	_	YES	Encoder		18 in	All	Flying leads	Screw terminal	10

AVIOU BUILD AVIOU BUOM AVIOU BUOM

	MRV22, MRV23, MRV32, MRV33,			ТО:				I DV10, AXIOM DV20, I PV10, AXIOM PV20,	
	411					CR6 OR CR15		O POINT PARTY	
Config Code	Replacement Part Number	Included with Drive	Туре	Description	Cable Length	Motor Size	CONNI Motor	ECTORS AT Axiom DV/PV 10	Axiom DV/PV Size
CR6	3604-1190	Optional	Power		6m	21 to 24	MS	Screw terminal	10
CR15	3604-1191	Optional	Power		15m	21 to 24	MS	Screw terminal	10
CR6	3604-1192	Optional	Power		6m	31 to 33	MS	Screw terminal	20
CR15	3604-1193	Optional	Power		15m	31 to 33	MS	Screw terminal	20
CR6	3604-1194	Optional	Power		6m	31 to 33	MS	Screw terminal	30
CR15	3604-1195	Optional	Power		15m	31 to 33	MS	Screw terminal	30
CR6	3604-1196	Optional	Encoder		6m	All	MS	Screw terminal	All
CR15	3604-1197	Optional	Encoder		15m	All	MS	Screw terminal	All



**BRUSHLESS** 

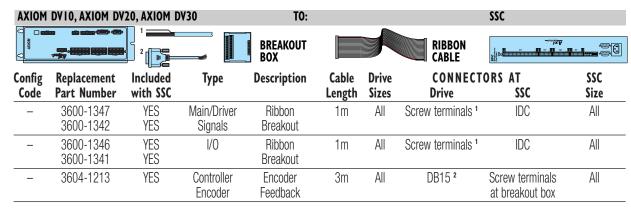
**Cables** 

### **AXIOM DV DRIVE TO SSC CONTROLLER**

MDV31 MDV33 MDV33 MDV34

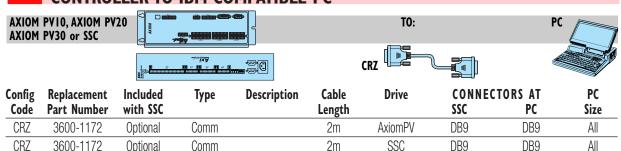
3600-1172

Optional



#### CONTROLLER TO IBM COMPATIBLE PC

Comm



2m

SSC

DB9

DB9

All

## Brushless Servo System

MOTOR STYLE, SIZE AND GEARHEAD REDUCTION

MRV 31Y

### **MOTOR TYPE**

MRV Brushless Servo Motor

#### MOTOR SIZE / DRIVE SIZE

MODEL	FRAME SIZE	STACK SIZE	DRIVE SIZE
11Y	17	1	Axiom DV10
21Y	23	1	Axiom DV10
22Y	23	2	Axiom DV10
23Y	23	3	Axiom DV10
24Y	23	4	Axiom DV10
31Y	34	1	Axiom DV10
31Z	34	1	Axiom DV20
32Y	34	2	Axiom DV20
32Z	34	2	Axiom DV30
33Y	34	3	Axiom DV20
33Z	34	3	Axiom DV30
51Y	56	1	Axiom DV30

Once motor type and frame size is selected, the appropriate adapter and couplers required are automatically chosen.

#### NO DRIVE OPTION

Replace Y or Z with X if motor drive X is NOT required (do not put 'Y' or 'Z' in string)

#### NO MOTOR OPTION

Motor(s) supplied by customer, Tol-XY\* O-Matic to mount using standard hardware and couplers

XJ\* Motor(s) supplied and mounted by customer, Tol-O-Matic to furnish standard hardware and couplers

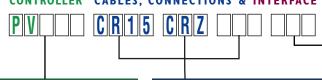
\* NOTE: For XY and XJ options, a full endface and shaft dimensional drawing must accompany the order for the actuator. Customer motors must be directly interchangeable with Tol-O-Matic motors.

#### **GEARHEAD REDUCTIONS**

(For In-line or Direct-Drive mounting configurations only)

MODEL	INPUT DIA.	MOTOR SIZE	REDUCTION RATIO
GHJ20	1/2-inch	23	5.5
GHJ21	1/2-inch	23	10
GHJ30	1/2-inch	34	5.5
GHJ31	1/2-inch	34	10

#### CONTROLLER CABLES, CONNECTIONS & INTERFACE



#### **CONTROLLER OR DRIVE COMBINATION**

#### SINGLE AXIS APPLICATIONS

PV Axiom®Plus Controller/Drive (Drive size is determined by "Y" or "Z" in motor code)

**\$\$C10** \*\*Stepper/Servo Controller, 1 axis application \*\* A 15 pin D-sub 36" connector cable for each servo axis will be included with the SSC controller when ordered with Axiom drive

#### MULTI AXIS APPLICATIONS

2 Axis Application

1st Axis 2nd Axis Servo Stepper Servo SSC22 Servo

3 Axis Application

	1st Axis	2nd Axis	3rd Axi
SSC31	Servo	Stepper	Steppe
SSC32	Servo	Stepper	Servo
SSC33	Servo	Servo	Steppe
SSC34	Servo	Servo	Servo

4 Axis Application

SSC41 SSC42 SSC43 SSC44 SSC45 SSC46 SSC47 SSC48	1st Axis Servo Servo Servo Servo Servo Servo Servo Servo	2nd Axis Stepper Stepper Stepper Servo Servo Servo Servo	3rd Axis Stepper Stepper Servo Servo Stepper Stepper Servo Servo	4th Axis Stepper Servo Stepper Servo Stepper Servo Stepper Servo
----------------------------------------------------------------------	----------------------------------------------------------------------------------	-------------------------------------------------------------------------------	------------------------------------------------------------------------------------------	------------------------------------------------------------------------------------------

**Product discontinued February 01, 2006:** 

B3B/M3B Belt Drive Actuator

>> REPLACED WITH B3W/M3W <<

>> SEE BROCHURE 3600-4148 <<

Contact Tol-O-Matic for repair parts

#### **CABLES**

#### FOR AXIOM DV OR AXIOM PV MUST SPECIFY ENCODER, **POWER CABLE LENGTH**

6-meter encoder cable, power CR6 cable

**CR15** 15-meter encoder cable, power

▲ MRV11 motor has flying leads, special cables are not required.

#### FOR SSC CONTROLLERS

If a 2-meter 9-pin RS232 cable is

A If ordering with AXIOM drive. controller encoder cables are included for each axis.

#### Indicate if breakout terminal and ribbon cables are needed.

No breakout terminals **BOY\*\*\*** With breakout terminals

#### \*\*\*BOY option includes:

- 60 pin/18" (457mm) ribbon cable & 60 pin breakout
- 26 pin/18" (457mm) ribbon cable & 26 pin breakout
- · If any axis configured w/ step & direction output -20 pin/18" (457mm) ribbon cable & 20 pin

breakout

#### **USER INTERFACE**

SIT Hand-held user interface JS Joy Stick

### TO ORDER ACTUATORS

B3S/M3S SERIES (SEE PAGE C-30) B3B/M3B SERIES (SEE PAGE C-50) **■ TKS SERIES** (SEE PAGE C-81)

■ TKB SERIES (SEE PAGE C-104)

BCS/MCS SERIES (SEE PAGE C-128) SLS/MLS SERIES (SEE PAGE C-138)

RSA/RSM SERIES (SEE PAGE D-53)

GSA/GSM SERIES (SEE PAGE E-36)



Not all codes listed are compatible with all options.

Use the Tol-O-Motion™ Sizing Software to determine available options and accessories based on your application requirements.

User manuals and software CD-ROM is included with any controller or drive ordered. Manuals and software are also available for download at www.tolomatic.com



#### **BRUSHLESS**

**System Ordering** 

## **Axione** Brushless Servo System FIELD RETROFIT ORDERING

	*SSC 1-4 CONTROLLERS					
Code	X-Axis	Y-Axis	Z-Axis	W-Axis	Part#	
SSC10	Servo	-	-	-	3600-0210	
SSC21	Servo	Stepper	-	-	3600-0221	
SSC22	Servo	Servo	-	-	3600-0222	
SSC31	Servo	Stepper	Stepper	-	3600-0231	
SSC32	Servo	Stepper	Servo	-	3600-0232	
SSC33	Servo	Servo	Stepper	-	3600-0233	
SSC34	Servo	Servo	Servo	-	3600-0234	
SSC41	Servo	Stepper	Stepper	Stepper	3600-0241	
SSC42	Servo	Stepper	Stepper	Servo	3600-0242	
SSC43	Servo	Stepper	Servo	Stepper	3600-0243	
SSC44	Servo	Stepper	Servo	Servo	3600-0244	
SSC45	Servo	Servo	Stepper	Stepper	3600-0245	
SSC46	Servo	Servo	Stepper	Servo	3600-0246	

NOTE: Any axis of the SSC may be changed by the insertion or removal of a jumper, see SSC manual #3600-4608

Servo

Servo

Stepper

Servo

3600-0247

3600-0248

\*Includes user manual and software CD-ROM

Servo

Servo



SSC47

SSC48

Servo

Servo

#### **BRUSHLESS**

Field Retrofit Ordering

	*AXIOM PV CONTROLLER / DRIVE				
Config. C	ode Includes	Part #			
PV10	Controller/Drive (order cables below)	3604-0008			
PV20	Controller/Drive (order cables below)	3604-0009			
PV30 Controller/Drive (order cables below) 3604-001		3604-0010			
*Includes user manual and software CD-ROM					

	*AXIOM DY DRIVE				
Config. Code	Includes	Part #			
DV10	Drive only (order cables below)	3604-0000			
DV20	Drive only (order cables below)	3604-0001			
DV30	Drive only (order cables below)	3604-0002			
DB20 cables are included as motor flying leads 3604-0003					
*Includes use	*Includes user manual and software CD-ROM				

MRV BRUSHLESS SERVO MOTORS			
Config. Code	Part #		
MRV11**	3600-6239		
MRV21	3600-6240		
MRV22	3600-6241		
MRV23	3600-6242		
MRV24	3600-6243		

MRV31	3600-6244
MRV32	3600-6245
MRV33	3600-6246
MRV51	3600-6247
## F B04 B 10 4 4 4 4	

** For RSA Rod Screw Actua	ators only
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USER INTERFACES	
Config. Code	Part #
SIT	3600-9161
JS	3600-9162

	CABLES	
Config Code	ltem	Part #
	20 pin breakout	3600-1340
	26 pin breakout	3600-1341
	60 pin breakout	3600-1342
	20 pin ribbon cable	3600-1345
	26 pin ribbon cable	3600-1346
	60 pin ribbon cable	3600-1347
CRZ	RS232 Cable	3600-1172
	SSC Encoder cable	3604-1213
RS23	32 - 9 Pin Adapter for MSS/MSD	3600-1186
RS	232 Cable Only for MSS/MSD	3600-1187
CR6 (DV10)	6m Motor Cable	3604-1190
CR6 (DV10)	6m Encoder Cable	3604-1196
CR15 (DV10)	15m Motor Cable	3604-1191
CR15 (Dv10)	15m Motor Cable	3604-1197
CR6 (DV20)	6m Motor Cable	3604-1192
CR6 (DV20)	6m Encoder Cable	3604-1196
CR15 (DV20)	15m Motor Cable	3604-1193
CR15 (DV20)	15m Encoder Cable	3604-1197
CR6 (DV30)	6m Motor Cable	3604-1194
CR6 (DV30 & MRV51)	6m Motor Cable	3604-1202
CR6 (DV30)	6m Encoder Cable	3604-1196
CR15 (DV30)	15m Motor Cable	3604-1195
CR15 (DV30 & MRV51)	15m Motor Cable	3604-1203
CR15 (DV30)	15m Encoder Cable	3604-1197

FIELD RETROFIT ORDERING	
- STEPPER	(SEE PAGE G-24)
- BRUSHED	DC (SEE PAGE H-27)