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ACS Controller and Omron CJ2M PLC EtherNet/IP Configuration Steps

Contents

1	Intro	duction2					
2	Overa	Overall Layout/Hardware2					
3	Tolon	Tolomatic ACS/TMI Setup					
4	Com	mmissioning PLC					
	4A	Set PLC Rotary Switches4					
	4B	Starting the PLC Project5					
	461	Configuring the I/O Table5					
	4C2	Editing the I/O Table6					
	4C3	Ethernet/IP Address Setting6					
	4C4	Changing Project Communications7					
	4C5	Setting PC to PLC comm's8					
	4D1	Launching "Network Configurator"9					
	4D2	Network Configurator9					
	4D3	Creating the Network Diagram10					

	4D4 Setting IP Addresses	10			
	4D5 Setting IP Addresses	11			
	4D6 Creating "Tag Sets" (input)	11			
	4D7 Creating "Tag Sets" (output)	12			
	4D8 Editing, Adding a Connection	12			
	4D9 Connection Details	13			
	4D10 Download Configuration!	13			
5A	ACS "Output Process Image"	14			
5B	ACS "Input Process Image"1				
6	PLC Data Exchange16				
7	Project References1				
8	Tag Set Up				
9	Tag Set Up Table18				



1. Introduction

This information contains primary steps required to commission the PLC and network configuration for operation of the ACS Drive with the Omron PLC. Drive-side information will be provided by Tolomatic.

Common PLC set-up will be identified, but not fully detailed herein.





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Tolomatic ACS / TMI Setup 3.





Figure 3.3; ACS Ethernet Properties

StaticIPAddress



4. Commission PLC

- A. Set PLC rotary switches as required Ethernet Modules Unit # and Node #
- B. Start project and connect via USB com.
- C. Register I/O table, set IP address, and Routing Table (if applicable, if using more than one SIOU card)
- D. Download, discon., change comm. to Ethernet

4A. Set PLC Rotary Switches

Setting Rotary Switches

Unit Number: 0-F, set to position 1

(Each communications module on the Rack ass'y must have a unique number up to 16 on a system. More than 1 will require a routing table be set via CX-Integrator.)

Node Number:

Set "16X1" Sw to 2, and 16X0 Sw to 7.

(These are "hex-based" settings which must match the last octet of software set IP address, this is done later via I/O table configuration.)

In this case 27 hex = 39 decimal, our IP is 10.0, 12.39 in this

example.



Figure 4A.1; Set PLC Rotary Switches (CJ2H)





Figure 4A.2; Set PLC Rotary Switches (CJ2M)



4B Starting the PLC Project



Figure 4C1.1; Configuring the I/O Table



4C2 Editing the I/O Table



Figure 4C3; Set IP Address



4C4 Changing Project Communications





4C5 Setting PC to PLC comm.'s

- 1. Change your PC's network card to an IP on the same subnet.
- 2. "Ping test" your conn. w/PLC.
- 3. Start, Run...



Figure 4C5.1; Setting PC to PLC comm.'s



4D1 Launching "Network Configurator"





4D3 Creating the Network Diagram



Figure 4D4.1; Setting IP Addresses



4D5 Setting IP Addresses



Figure 4D6.1; Creating "Tag Sets" (input)



4D7 Creating "Tag Sets" (output)

- 1. Click the "Out-Produce" tab.
- 2. Click "Edit Tags"
- Enter an address in the "Name" field.

(As before, this is actually the address location you wish to designate in the PLC for use in controlling the ACS)

4. Choose "Register".

> (Since this completes the Output tag sets we need here click "Close" and then "OK")



4D8 Editing, adding a Connection



Figure 4D8.1; Editing, adding a Connection



4D9 Connection Details



Figure 4D10.1; Download Configuration!



5A ACS "Output Process Image"



Figure 5A.1; ACS "Output Process Image"



5B ACS "Input Process Image"



Figure 5B.1; ACS "Input Process Image"



6 PLC Data Exchange

CJ2M and Tolo ACS wERD over EIP - CX-Programmer - [[Stopped] - CJ2M_and	[Tolo_ACS.NewProgram1.Section1 [Diagram]]
C File Edit View Insert PLC Program Simulation Tools Window	
U	
RewProject Democratic ACSICI2MI Stop/Program	
Data Types	
- 👷 Symbols	
Settings	. Create Symbols, (not done here yet) and pull data into
- Memory card	Watch Window to test run
- B Error log	
- Memory	
Programs	
Symbols	
- @ Section1	
END END	
Prince (
PLC Name Name	
CJ2M_and_Tolo_ACS	
CJ2M_and_Tolo_ACS CJ2M_and_Tolo_ACS	
CJ2M_and_Tolo_ACS	\frown
CJ2M_and_Tolo_ACS W206	16BIT (Binary, Channel) 0000 00 0000 0000 0000 0000
Figure 6.1: PLC Data Exchange	
7 Project References	
Omron CV Programmer Pot manuals	Installed with Suite
	s, installed with Suite
Omron Network Config. Tool for "E/IP -	- Ref manuals
 CJ2M Manuals – available at Omron2 	47.com
 Tolomatic Motion Interface, EDS files and 	nd manuals at Tolomatic.com
	O Tolomotio
DECLEMENT	
HARDWARE & INSTALLATION	ETHERNET/IP
GUIDE	PROGRAMMER'S GUIDE
ACS - Actuator Control Solutions	ACS Drive/Controller
Stepper Drive/Controller and Motors	
10 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
B B	
and the second second	20-01,0
LINEAR SOLUTIONS MADE EASY.	LINEAR SOLUTIONS MADE EASY.
Figure 7.1 Telemetic #2604_4172	Figure 7.2 Telematic #2600_4167
riyuie 7.1 IUlullialic #3004-4173	riyult 1.2 1010111aut #3000-410/

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8 Tag Set Up



Figure 8.1; Double click on symbols, edit the data tag. A list of tags/addresses needs to be made for each ACS parameter.

PLC Na	Name	Address	Data Type Format FB Vsage	Value	Value(Binary)
NewPLC1	FORCE_LOAD	D100	REAL (Floating Point,)	+100.0000 Float	+100.0000 Float
NewPLC1	VELOCITY_LOAD	0120	REAL (Neating Point	+50.00000 Float	+50.00000 Float
NewPLC1	ACCEL_LOAD	D130	REAL (Eloating Point,	+100.0000 Float	+100.0000 Float
NewPLC1	DECEL_LOAD	0140	REAL (Floating Point	+100.0000 Float	+100.0000 Float
NewPLC1	TARGET_POS_LOAD	D1000	REAL (Floating Point,	+87.00000 Float	+87.00000 Float
NewPLC1	MOTION TYPE			5	2 0000 0000 0000
NewPLC1	ACS_EMABLE Set New	Value	\sim		5
NewPLC1	ACS START M				-1
NewPLC1	ACS_HOME	non refue	10	Set Value	
NewPLC1	ACS ESTOP Value	× +87.0	0000 Float	Close	1
NewPLC1	ACS_MOVE_SEL New	And the			
New PLC1	TARGET_POS_L	value.		Edit Address/Tup	00000 Float
NewPLCL	ACS_TARGET P 3402	2823e+38 to	-1.175495e-38,		00000 Float
NewPLC1	ACS_VELOCITY +1 17	54959-39 to	10,00000000000000000000000000000000000	Binary >>	00000 Float
New ALC1	ACS_ACCEL	34396-3010	13.4020236430 (2011)		0.0000 Float
NewPLC1	ACS_DECEL	W208	KEAL (Floating Point,	+100.0000 Float	+100.0000 Float
NewPLC1	ACS_FORCE	W210	REAL (Floating Point,	+100.0000 Float	+100.0000 Float
New PLC1	ACS_MOTION_TYPE	W212	DWORD (Hex,Double	0,D	0000 0000 0000 0000 0000 0000 0000 00
NewPL C1	ACS_SUBRENT_POS	W300	REAL (Floating Point,	+86.96960 Float	+86.96960 Float
NewPLC1	ACS_DRIVE_STATUS	W302	DWORD (Hex, Double	-2147483646,D	1000 0000 0000 0000 0000 0000 0000 00
NewPLC1	ACS_DRIVE_FAULT_FL	W304	DWORD (Hex, Double	0,D	0000 0000 0000 0000 0000 0000 0000 00

Figure 8.2; Data tag values can be loaded by double clicking the tag.



9 Tag Set Up Tables



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